

EECS498-003 Formal Verification of Systems Software

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Chapter 3: State Machines



Building state machines

A state is an assignment of values to variables

An action is a transition from one state to another

An execution is a sequence of states

We will capture executions with state machines



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The Switch state machine





The Game of Nim



The Nim state machine

```
datatype Variables = Variables(tokens:nat)
predicate Init(v:Variables) {
    v.tokens > 0
}
predicate Play(v:Variables, v':Variables, take:nat) {
    && 1 <= take <= 4
&& v'.tokens == v.tokens - take
                                        > enabling condition
                                            "update"
}
predicate Next(v:Variables, v':Variables)
    exists take :: Play(v, v', take)
}
```



Administrivia

- Remember that Problem Set 1 is due next Thursday, September 19
- My office hours today were moved to 5-6pm



A simple library app

```
datatype Card = Shelf | Patron(name:
string)
datatype Book = Book(title: string)
type Variables = map<Book, Card>
```

Small-library rule: each patron can have at most one book checked out

A state is an assignment of values to variables

datatype Card = Shelf | Patron(name: string) datatype Book = Book(title: string) type Variables = map<Book, Card>

The state space is the set of possible assignments.





An execution is an infinite sequence of states





A behavior is the set of all possible executions



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A state machine definition datatype Card = Shelf | Patron(name:

predicate Init(v: Variables) {

}

&& book in v

&& v[book] == Shelf

string) datatype Book = Book(title: string) type Variables = map<Book, Card> forall book | book in v :: v[book] == Shelf predicate CheckOut(v : Variables, v' : Variables, book: Book, name: string) {

```
enabling condition
"update"
  && (forall book | book in v :: v[book] != Patron(name))
  && v' == v[book := Patron(name)]
predicate CheckIn(v : Variables, v' : Variables, book: Book, name: string) {
  && book in v
  && v[book] == Patron(name)
  && v' == v[book := Shelf]
```

predicate Next(v: Variables, v': Variables) { (exists book, name :: CheckOut(v, v', book, name)) (exists book, name :: CheckIn(v, v', book, name))

Nondeterministic definition



A behavior is the set of all possible executions

```
predicate CheckOut(v, v', book, name) {
  && book in v
  && v[book] == Shelf
  && (forall book | book in v :: v[book] !=
Patron(name))
 && v' == v[book := Patron(name)]
}
predicate CheckIn(v, v', book, name) {
  && book in v
 && v[book] == Patron(name)
 && v' == v[book := Shelf]
}
```





How should we define a behavior?

With a **program**?

Its variables define its state space Its executions define its behavior

Weaknesses:

- concreteness
- nondeterminism
- asynchrony
- environment



How should we define a behavior?

With a state machine

Its type defines its state space Its initial states and transitions define its behavior

State machine strengths

- Abstraction
 - States can be abstract
 - Model an infinite map instead of an efficient pivot table
 - Next predicate is nondeterministic:
 - Implementation may only select some of the choices
 - Can model Murphy's law (e.g. crash tolerance) or an adversary



State machine strengths

- Abstraction
- Asynchrony
 - Each step of a state machine is conceptually atomic
 - Interleaved steps capture asynchrony: threads, host processes, adversaries
 - Designer decides how precisely to model interleaving; can refine/reduce

State machine strengths

- Abstraction
- Asynchrony
- Environment
 - Model a proposed program with one state machine (verified)
 - Model (adversarial) environment with another (trusted)
 - Compound state machine models their interactions (trusted)



